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SELECTION PROCEDURES FOR A PROBLEM IN ANALYSIS OF VARIANCE.(U)

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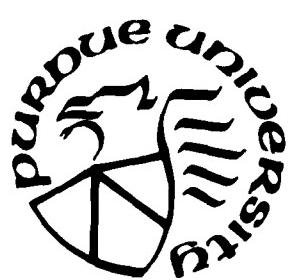
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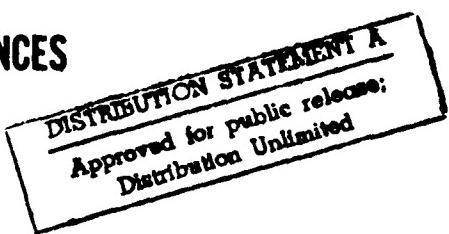
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Selection Procedures for A
Problem in Analysis of Variance*

by

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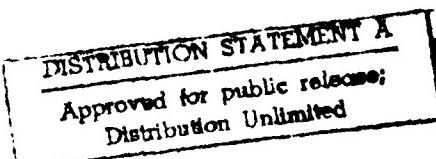
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Selection Procedures For A
Problem in Analysis of Variance*

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1. Introduction

For a completely randomized block design with one observation per cell, we express the observable random variables $x_{i\alpha}$ ($i = 1, \dots, k$; $\alpha = 1, \dots, n$) as

$$(1.1) \quad x_{i\alpha} = \mu + \beta_\alpha + \tau_i + \epsilon_{i\alpha}, \quad \sum_{i=1}^k \tau_i = 0,$$

where μ is the mean-effect, β_1, \dots, β_n are the block effects (nuisance parameters for the fixed effects model), τ_1, \dots, τ_k are the treatment effects, and $\epsilon_{i\alpha}$ are the error components. We assume that the errors within each block are jointly normally distributed.

We assume that the quality of a treatment is judged by the largeness of the τ_i 's. A 'population' π_i is called the best if τ_i is the largest. In general, it may be complicated to derive suitable tests for appropriate hypotheses, in which the experimenter may really be interested. We apply the subset selection approach (using certain basic hypotheses) and thus obtain more appropriate information regarding the treatments. A subset selection procedure is designed to select a subset so as to include the best population. Selection of any subset that contains the best is called a correct selection (CS). Roughly speaking, any two populations that are in the same selected subset, will be considered as "equivalently good". If all populations are selected, we claim that all treatments are homogeneous. In general, for achieving the objective of the experimenter, one should establish a suitable set of basic hypotheses. Depending on the objective one should proceed to consider different

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ways of formulating the basic hypotheses. In this paper, we discuss a method based on subset selection rules for the purpose of making a claim of the type: $\tau_i = \tau^* > \tau_j + \Delta$ for all $i \in I$ and $j \in J$, where I and J form a partition of $\{1, 2, \dots, k\}$. The process of making such a claim will be called hypothesis identification. This is achieved by setting up certain basic hypotheses regarding the τ_i 's and using a subset selection procedure to test these basic hypotheses. It should be pointed out that in identifying an appropriate hypothesis, we assume that the constant Δ in the claim is specified by the experimenter, say, based on past experience. Associated with the tests of the basic hypotheses using a selection rule, there are error probabilities and the infimum of the probability of a correct selection for the rule employed. These are related to the power function of these tests. The sum of the average (over the basic hypotheses tested) of the error probabilities and one minus the infimum of the probability of a correct selection is called the identification risk. The main theorem of the paper discusses the derivation of an optimal selection rule in the sense of minimizing the identification risk. For a more general theory of multiple decisions from ranking and selection approach, one can refer to a recent monograph by Gupta and Huang (1981). A general survey of the entire field is provided in Gupta and Panchapakesan (1979).

Let $\underline{\gamma}$ be a random observable vector with probability distribution depending upon a parameter $\underline{\tau}' = (\tau_1, \dots, \tau_k) \in \Omega$. Consider a family of hypotheses testing problems as follows:

$$(1.2) \quad H_0: \underline{\tau} \in \Omega_0 \text{ vs } H_i: \underline{\tau} \in \Omega_i, 1 \leq i \leq k,$$

where $\Omega_0 = \{\underline{\tau} | \tau_1 = \dots = \tau_k\}$ and $\Omega_i = \{\underline{\tau} | \tau_i > \max_{j \neq i} \tau_j\}$, $i = 1, 2, \dots, k$. A test of the hypotheses (1.2) will be defined to be a vector $(\delta_1(\underline{y}), \dots, \delta_k(\underline{y}))$, where the elements of the vector are ordinary test functions; when \underline{y} is observed

we reject H_0 in favor of H_i with probability $\delta_i(y)$, $1 \leq i \leq k$. The power function of a test $(\delta_1, \dots, \delta_k)$ is defined to be the vector $(\beta_1(\underline{\tau}), \dots, \beta_k(\underline{\tau}))$, where $\beta_i(\underline{\tau}) = E_{\underline{Y}} \delta_i(\underline{Y})$, $1 \leq i \leq k$. For $\underline{\tau} \in \Omega_i$, $\beta_i(\underline{\tau})$ is the probability of a correct selection $P(CS)$ and $\delta_i(y)$ is the individual selection probability of selecting the best population π_i . Let S_y be the set of all the tests $(\delta_1, \dots, \delta_k)$ such that

$$(1.3) \quad E_{\underline{\tau}} \delta_i(\underline{Y}) \leq \gamma, \quad \underline{\tau} \in \Omega_0, \quad 1 \leq i \leq k,$$

where γ is the upper bound on the error probabilities associated with the treatment effects.

For each i , ($1 \leq i \leq k$), we would like to have $\beta_i(\underline{\tau})$ large when $\underline{\tau} \in \Omega_i$ subject to (1.3). For $\underline{\tau} \in \Omega_j$, if we make $\beta_j(\underline{\tau})$ large, then $\beta_j(\underline{\tau})$ should be small for $j \neq i$.

It should be pointed out that in the formulation and proof of the optimal selection procedure, results from Neyman-Pearson theory are used.

2. Formulation of an Optimal Selection Procedure

Assume that

$$\underline{x}'_\alpha = (x_{1\alpha}, \dots, x_{k\alpha}),$$

$\alpha = 1, \dots, n$, are independently and identically distributed random vectors with the following distribution:

$$(2.1) \quad (2\pi\sigma^2)^{-\frac{1}{2}kn} |\Lambda|^{-\frac{1}{2}} \exp[-\frac{1}{2\sigma^2} (\underline{x} - \underline{\theta})' \Lambda^{-1} (\underline{x} - \underline{\theta})],$$

where $\underline{x}' = (x_{11}, \dots, x_{k1}; \dots; x_{1n}, \dots, x_{kn})$ and $\underline{\theta}' = (\theta_{11}, \dots, \theta_{k1}; \dots; \theta_{1n}, \dots, \theta_{kn})$, $\theta_{i\alpha} = \mu + \beta_\alpha + \tau_i$, $i = 1, \dots, k$; $\alpha = 1, 2, \dots, n$ and Λ is a known positive definite $kn \times kn$ correlation matrix defined as follows:

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$$\Lambda = (\lambda_{ij})_{kn \times kn}$$

$$= \begin{bmatrix} \Lambda_1 & 0 & \dots & 0 \\ 0 & \Lambda_1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \Lambda_1 \end{bmatrix}, \quad \text{where}$$

$$\Lambda_1 = \begin{bmatrix} 1 & \lambda \\ \lambda & 1 \end{bmatrix}_{k \times k}.$$

We rewrite the original model as the general linear model as follows:

$$\underline{x} = \underline{\theta} + \underline{\epsilon}, \quad \underline{\epsilon} \sim N(\underline{0}, \sigma^2 \Lambda).$$

Since we are interested in the difference between all pairs of τ_i 's, we transform the linear model to the following: For any i , let

$$Y_i = C \underline{\tau}_i + \underline{\eta}, \quad \underline{\eta} \sim N(\underline{0}, \sigma^2 \Sigma_i),$$

where $\underline{\tau}_i^t = (\tau_{i1}, \dots, \tau_{ik})$, $\tau_{ij} = \tau_i - \tau_j$, $j \neq i$,

$$Y_i^t = (Y_{i11}, \dots, Y_{ik1}; \dots; Y_{i1n}, \dots, Y_{ikn})_{1 \times (k-1)n}$$

$$Y_{ij\ell} = X_{i\ell} - X_{j\ell}, \quad i \neq j; \quad i, j = 1, \dots, k; \quad \ell = 1, \dots, n,$$

$$Y_i = A_i \underline{x}, \quad \underline{\eta} = A_i \underline{\epsilon}$$

$$A_i = \begin{bmatrix} A_{i1} & & & \\ & A_{i1} & 0 & \\ 0 & & \ddots & \\ & & & A_{i1} \end{bmatrix}_{(k-1)n \times kn}$$

$$\Sigma_i = A_i \wedge A_i^t = \begin{bmatrix} A_{i1} \wedge_1 A_{i1}^t & & \\ & \ddots & 0 \\ 0 & & A_{i1} \wedge_1 A_{i1}^t \end{bmatrix}_{(k-1)n \times (k-1)n},$$

$$A_{i1} = \begin{bmatrix} & & i \\ -1 & 0 & \dots & 0 & 1 & 0 & \dots & 0 \\ 0 & -1 & 0 & \dots & 0 & 1 & 0 & \dots & 0 \\ \dots & & & & & & & \\ 0 & \dots & 0 & -1 & 1 & 0 & \dots & 0 \\ 0 & \dots & 0 & 1 & -1 & 0 & \dots & 0 \\ \dots & & & & & & & \\ 0 & \dots & 0 & 1 & 0 & \dots & 0 & -1 \end{bmatrix}_{(k-1) \times k}$$

$$C' = [I, \dots, I]_{(k-1) \times (k-1)n}$$

where each of the identity matrix in C' is $(k-1) \times (k-1)$.

The maximum likelihood estimator of $\underline{\lambda}_i$ is as follows:

$$\hat{\underline{\lambda}}_i = (C' \Sigma_i^{-1} C)^{-1} C' \Sigma_i^{-1} \underline{y}_i.$$

Since,

$$A_{i1} \wedge_1 A_{i1}^t = (1-\lambda) \begin{bmatrix} 2 & & \\ & 1 & \\ & & 2 \end{bmatrix}_{(k-1) \times (k-1)}$$

$$(A_{i1} \wedge_1 A_{i1}^t)^{-1} = (1-\lambda)^{-1} \frac{1}{k} \begin{bmatrix} k-1 & -1 & & \\ & \ddots & & \\ -1 & & k-1 & \end{bmatrix} = V_i$$

$$C' \Sigma_i^{-1} C = n (A_{i1} \wedge_1 A_{i1}^t)^{-1} = \frac{n}{k(1-\lambda)} \begin{bmatrix} k-1 & -1 & & \\ & \ddots & & \\ -1 & & k-1 & \end{bmatrix}$$

$$(C' \Sigma_i^{-1} C)^{-1} = \frac{1-\lambda}{n} \begin{bmatrix} 2 & & \\ & 1 & \\ & & 2 \end{bmatrix}_{(k-1) \times (k-1)},$$

$$C' \Sigma_i^{-1} = [I \dots I] \begin{bmatrix} v_i & 0 \\ 0 & \cdot v_i \end{bmatrix}$$

$$= [v_i, \dots, v_i]$$

$$(C' \Sigma_i^{-1} C)^{-1} C' \Sigma_i^{-1} = \frac{1-\lambda}{n} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} [v_i, \dots, v_i]$$

$$= \frac{1}{n} [I, \dots, I].$$

Hence,

$$\hat{\tau}_i = (C' \Sigma_i^{-1} C)^{-1} C' \Sigma_i^{-1} y_i$$

$$= \frac{1}{n} \begin{bmatrix} \sum_{\ell=1}^n y_{i1\ell} \\ \vdots \\ \sum_{\ell=1}^n y_{ik\ell} \end{bmatrix} = \begin{bmatrix} y_{i1} \\ \vdots \\ y_{ik} \end{bmatrix} = \begin{bmatrix} \bar{x}_i - \bar{x}_1 \\ \vdots \\ \bar{x}_i - \bar{x}_k \end{bmatrix},$$

$$\text{where } \bar{x}_i = \frac{1}{n} \sum_{j=1}^n x_{ij}, \quad 1 \leq i \leq k.$$

The joint density of $y_{i11}, \dots, y_{i1k}; \dots; y_{i1n}, \dots, y_{ikn}$ is the following:

$$p_{\tau_i}(y_i) = (2\pi\sigma^2)^{-\frac{1}{2}k} |\Sigma_i|^{-\frac{1}{2}} \exp\left[-\frac{1}{2\sigma^2} (y_i - C_{\tau_i})' \Sigma_i^{-1} (y_i - C_{\tau_i})\right]$$

where

$$\Sigma_i = A_i \wedge A_i' = (1-\lambda) \begin{bmatrix} J & 0 \\ 0 & J \end{bmatrix} (k-1) \times (k-1)$$

$$J = \begin{bmatrix} 2 & 0 \\ 0 & \cdot 2 \end{bmatrix} (k-1) \times (k-1).$$

$$\Sigma_i^{-1} = \begin{bmatrix} v_i & 0 \\ 0 & \cdot v_i \end{bmatrix}.$$

Now, we specify the Ω_i 's as follows (Note that this is a different specification from that given earlier):

$$\Omega_i = \{\underline{\tau} \mid \tau_i \geq \max_{j \neq i} \tau_j + \Delta\sigma\}, \quad 1 \leq i \leq k,$$

and

$$\bar{\Omega} = \bigcup_{i=1}^k \Omega_i.$$

Assume that σ is known. Let

$$\underline{\Delta}_i^t = (\Delta\sigma, \dots, \Delta\sigma)_{1 \times (k-1)}, \quad i = 1, \dots, k, \quad \Delta > 0.$$

Thus

$$\begin{aligned} \frac{p_{\underline{\Delta}_i^t}(y_i)}{p_0(y_i)} &= \exp \frac{1}{2\sigma^2} \{ -(\underline{y}_i - C\underline{\Delta}_i^t)' \Sigma_i^{-1} (\underline{y}_i - C\underline{\Delta}_i^t) + \underline{y}_i' \Sigma_i^{-1} \underline{y}_i \} \\ &= \exp \left\{ \frac{1}{\sigma^2} \underline{\Delta}_i^t C' \Sigma_i^{-1} \underline{y}_i - \frac{1}{2\sigma^2} \underline{\Delta}_i^t C' \Sigma_i^{-1} C \underline{\Delta}_i^t \right\} \\ &= \exp \left\{ \frac{n\Delta}{(1-\lambda)k\sigma} (y_{i1} + \dots + y_{ik}) - \frac{1}{2\sigma^2} \underline{\Delta}_i^t C' \Sigma_i^{-1} C \underline{\Delta}_i^t \right\}. \end{aligned}$$

Hence, we can rewrite

$$\frac{p_{\underline{\Delta}_i^t}(y_i)}{p_0(y_i)} \geq d' \quad \text{as} \\ y_{i1} + \dots + y_{ik} \geq d''\sigma.$$

Let a selection rule $\delta^0 = (\delta_1^0, \dots, \delta_k^0)$ be defined by

$$\delta_i^0(y_i) = \begin{cases} 1 & \text{if } p_{\underline{\Delta}_i^t}(y_i) \geq d' p_0(y_i), \\ 0 & \text{otherwise} \end{cases},$$

such that

$$(2.2) \quad E_{\underline{\tau}} \delta_i^0(y_i) = \gamma, \quad \underline{\tau} \in \Omega_0. \quad \text{Then}$$

δ^0 maximizes

$$(2.3) \quad \inf_{\Omega} P(CS|\delta)$$

among all selection rules $\delta \in S(\gamma)$.

Note that $\delta_i^0(y_i)$ is also based on the maximum likelihood estimators $\hat{\tau}_i$ of τ_i . Since for any $\delta \in S(\gamma)$,

$\tau \in \bar{\Omega} = \bigcup_{i=1}^k \Omega_i$ implies $\tau \in \Omega_i$ for some i , thus

$$\begin{aligned} P(CS|\delta) &= \int \delta_i(y_i) p_{\tau}(y_i) d\nu(y_i) \\ &\geq \min_{1 \leq i \leq k} \inf_{\tau \in \Omega_i} \int \delta_i(y_i) p_{\tau}(y_i) d\nu(y_i). \end{aligned}$$

We have

$$\inf_{\tau \in \bar{\Omega}} P(CS|\delta) = \min_{1 \leq i \leq k} \inf_{\tau \in \Omega_i} \int \delta_i(y_i) p_{\tau}(y_i) d\nu(y_i).$$

For any $\delta \in S(\gamma)$, it follows that

$$\int (\delta_i - \delta_i^0)(p_{\Delta_i} - dp_0) \leq 0$$

which implies

$$\int \delta_i^0 p_{\Delta_i} \geq \int \delta_i p_{\Delta_i}.$$

Since $\delta_i^0(y_i)$ is nondecreasing in y_i , hence

$$\begin{aligned} \inf_{\tau \in \bar{\Omega}} P(CS|\delta^0) &= \min_{1 \leq i \leq k} \int \delta_i^0(y_i) p_{\Delta_i}(y_i) d\nu(y_i) \\ &\geq \min_{1 \leq i \leq k} \int \delta_i(y_i) p_{\Delta_i}(y_i) d\nu(y_i) \\ &\geq \min_{1 \leq i \leq k} \inf_{\tau \in \Omega_i} \int \delta_i(y_i) p_{\tau}(y_i) d\nu(y_i) \\ &= \inf_{\theta \in \bar{\Omega}} P(CS|\delta). \end{aligned}$$

We rewrite δ^0 as follows:

$$\delta_i^0(y_i) = \begin{cases} 1 & \text{if } y_{i1} + \dots + y_{ik} \geq d''\sigma, \\ 0 & \text{otherwise} \end{cases}$$

Thus, the optimal subset selection rule is as follows:

$$\delta_i^0(\underline{x}) = \begin{cases} 1 & \text{if } \bar{x}_i \geq \frac{1}{k-1} \sum_{j \neq i} \bar{x}_j + d\sigma, \\ 0 & \text{otherwise} \end{cases},$$

$$\text{where } d = \frac{d''}{k-1}.$$

Now, we wish to determine d and n . We make the following transformation:

$$z_{ik} = [1 \dots 1]_{1 \times (k-1)} \begin{bmatrix} y_{i1} \\ \vdots \\ y_{ik} \end{bmatrix}, \text{ and}$$

$$\tau = \tau_{i1} + \dots + \tau_{ik} = (k-1)\tau_i - \sum_{j \neq i} \tau_j.$$

Since the distribution of

$$\hat{\underline{\tau}}_i = \begin{bmatrix} \hat{\tau}_{i1} \\ \vdots \\ \hat{\tau}_{ik} \end{bmatrix} = (\mathbf{C}' \Sigma_i^{-1} \mathbf{C})^{-1} \mathbf{C}' \Sigma_i^{-1} \mathbf{y}_i$$

is $(2\pi\sigma^2)^{-\frac{k}{2}} |\Sigma_{1i}|^{-\frac{1}{2}} \exp[-\frac{1}{2\sigma^2} (\hat{\underline{\tau}}_i - \underline{\tau}_i)' \Sigma_{1i}^{-1} (\hat{\underline{\tau}}_i - \underline{\tau}_i)]$, where $\Sigma_{1i} = \frac{1-\lambda}{n} \mathbf{J}$.

Then the distribution of Z_{ik} is

$$[2\pi\sigma^2(1-\lambda)k(k-1) \frac{1}{n}]^{-\frac{1}{2}} \exp[-\frac{n}{2\sigma^2(1-\lambda)k(k-1)} (z_{ik} - \tau)^2].$$

Hence

$$\begin{aligned} E_0 \delta_i^0(\underline{y}_i) &= P(Z_{ik} \geq d''\sigma) \\ (2.4) \quad &= \Phi\left[-\frac{d''\sqrt{n}}{\sqrt{(1-\lambda)k(k-1)}}\right] = \gamma, \end{aligned}$$

and

$$\begin{aligned}
 & \inf_{\underline{\tau} \in \bar{\Omega}} P_{\underline{\tau}} (CS | \delta^0) \\
 &= \min_{1 \leq i \leq k} \int \delta_i^0(y_i) p_{\Delta_i}(y_i) d\nu(y_i) \\
 &= \min_{1 \leq i \leq k} P_{\Delta_i}(Z_{ik} \geq d''\sigma) \\
 &= \min_{1 \leq i \leq k} P_{\Delta_i}\left(\frac{(Z_{ik} - (k-1)\Delta)\sqrt{n}}{\sqrt{(1-\lambda)k(k-1)}} \geq \frac{(d'' - (k-1)\Delta)\sqrt{n}}{\sqrt{(1-\lambda)k(k-1)}}\right) \\
 (2.5) \quad &= \Phi\left[-\frac{(d'' - (k-1)\Delta)\sqrt{n}}{\sqrt{(1-\lambda)k(k-1)}}\right] = p*.
 \end{aligned}$$

For given r , P^* , k , λ , and Δ , we can find d'' and the smallest number of blocks, n , to satisfy equations (2.4) and (2.5). Note that this n is also the minimum sample size for the case of one observation per cell in the completely randomized block design.

We rewrite (2.4) and (2.5) as

$$\Phi\left[-\frac{d\sqrt{n(k-1)}}{\sqrt{(1-\lambda)k}}\right] = \gamma$$

and

$$\Phi\left[-\frac{(d-\Delta)\sqrt{n(k-1)}}{\sqrt{(1-\lambda)k}}\right] = p*.$$

Let z_{p*} and z_γ represent the upper percentage points corresponding to p^* and γ , respectively of the standard normal distribution. Then we have

$$d = -\frac{z_\gamma \Delta}{z_{p*} - z_\gamma},$$

and

$$n = \left\lceil \frac{(1-\lambda)k(z_{p*} - z_\gamma)^2}{(k-1)\Delta^2} \right\rceil,$$

where $\lceil a \rceil$ is the smallest integer greater than or equal to a .

Summarizing the previous results, we obtain the following theorem.

Theorem: Under model (1.1) with the stated assumption on ϵ_α , an optimal procedure for selecting a subset of the "best" or "worthwhile" treatments based on the observed data \underline{x} and satisfying the conditions (2.2) and (2.3) is: Select the population π_i with probability $\delta_i^0(\underline{x})$ given by

$$\delta_i^0(\underline{x}) = \begin{cases} 1 & \text{if } \bar{x}_i \geq \frac{1}{k-1} \sum_{j \neq i} \bar{x}_j + d\sigma, \\ 0 & \text{otherwise} \end{cases},$$

where the smallest values of d and n are given by

$$d = - \frac{z_Y^\Delta}{z_{P^*} - z_Y},$$

and

$$n = \left\lfloor \frac{(1-\lambda)k(z_{P^*} - z_Y)^\Delta}{(k-1)\Delta^2} \right\rfloor.$$

Furthermore, we have established the following connection between the selection procedure and the hypothesis identification problem as follows:

If $\pi_{i_1}, \pi_{i_2}, \dots, \pi_{i_j}$ ($j < k$) are selected, we say that these populations are homogeneous and make the hypothesis identification

$$H_i^1: \tau_{i_1} = \dots = \tau_{i_j} \geq \max_{\substack{1 \leq l \leq k \\ l \notin \{i_1, \dots, i_j\}}} \tau_l + \Delta\sigma.$$

Note that the overall identification risk connected with this problem is $\leq \gamma + (1-P^*)$.

Remark: It should be pointed out that for some pairs (γ, P^*) , δ^0 may not select any population. This is to be interpreted as not identifying any one of the appropriate hypotheses.

We consider some special cases to provide an idea as to the appropriate identification of one of the hypotheses. For $\gamma = 0.05, \lambda = 0.5$ and $P^* = 0.95, 0.90, 0.80$; then

(i) $k = 2$,

$$H_0: \tau_1 = \tau_2, H'_1: \tau_1 \geq \tau_2 + \Delta\sigma, H'_2: \tau_2 \geq \tau_1 + \Delta\sigma.$$

In this case, for specified Δ -values, the smallest d and n needed for the optimal selection rule are given in the following table.

Δ	0.1	0.5	1.0	2.0
$d(0.95, 0.90, 0.80)$	0.05, 0.06, 0.07	0.25, 0.32, 0.33	0.50, 0.64, 0.66	1.00, 1.29, 1.33
$n(0.95, 0.90, 0.80)$	1089, 858, 620	44, 35, 25	11, 9, 7	3, 3, 2

(ii) $k = 3$,

$$H_0: \tau_1 = \tau_2 = \tau_3, \quad H'_1: \tau_1 \geq \max(\tau_2, \tau_3) + \Delta\sigma,$$

$$H'_2: \tau_2 \geq \max(\tau_1, \tau_3) + \Delta\sigma, \quad H'_3: \tau_3 \geq \max(\tau_1, \tau_2) + \Delta\sigma,$$

$$H'_4: \tau_1 = \tau_2 \geq \tau_3 + \Delta\sigma, \quad H'_5: \tau_1 = \tau_3 \geq \tau_2 + \Delta\sigma,$$

$$H'_6: \tau_2 = \tau_3 \geq \tau_1 + \Delta\sigma.$$

For optimal selection rule, the minimum value of d and n are computed (for specified values of Δ) and given in the following table.

Δ	0.1	0.5	1.0	2.0
$d(0.95, 0.90, 0.80)$	0.05, 0.06, 0.07	0.25, 0.32, 0.33	0.50, 0.64, 0.66	1.00, 1.29, 1.33
$n(0.95, 0.90, 0.80)$	817, 644, 465	33, 26, 19	9, 7, 5	3, 2, 2

(iii) $k = 4$,

$$H_0: \tau_1 = \tau_2 = \tau_3 = \tau_4, \quad H'_1: \tau_1 \geq \max(\tau_2, \tau_3, \tau_4) + \Delta\sigma,$$

- $$H_2^i: \tau_2 \geq \max(\tau_1, \tau_3, \tau_4) + \Delta\sigma, \quad H_3^i: \tau_3 \geq \max(\tau_1, \tau_2, \tau_4) + \Delta\sigma,$$
- $$H_4^i: \tau_4 \geq \max(\tau_1, \tau_2, \tau_3) + \Delta\sigma, \quad H_5^i: \tau_1 = \tau_2 \geq \max(\tau_3, \tau_4) + \Delta\sigma,$$
- $$H_6^i: \tau_1 = \tau_3 \geq \max(\tau_2, \tau_4) + \Delta\sigma, \quad H_7^i: \tau_1 = \tau_4 \geq \max(\tau_2, \tau_3) + \Delta\sigma,$$
- $$H_8^i: \tau_2 = \tau_3 \geq \max(\tau_1, \tau_4) + \Delta\sigma, \quad H_9^i: \tau_2 = \tau_4 \geq \max(\tau_1, \tau_3) + \Delta\sigma,$$
- $$H_{10}^i: \tau_3 = \tau_4 \geq \max(\tau_1, \tau_2) + \Delta\sigma, \quad H_{11}^i: \tau_1 = \tau_2 = \tau_3 = \tau_4 \geq \Delta\sigma,$$
- $$H_{12}^i: \tau_1 = \tau_2 = \tau_4 \geq \tau_3 + \Delta\sigma, \quad H_{13}^i: \tau_1 = \tau_3 = \tau_4 \geq \tau_1 + \Delta\sigma,$$
- $$H_{14}^i: \tau_2 = \tau_3 = \tau_4 \geq \tau_1 + \Delta\sigma.$$

For the optimal selection rule, the minimum value of d and n are computed (for specified values of Δ) and given in the following table.

Δ	0.1	0.5	1.0	2.0
$d(0.95, 0.90, 0.80)$	0.05, 0.06, 0.07	0.25, 0.32, 0.33	0.50, 0.64, 0.66	1.00, 1.29, 1.33
$n(0.95, 0.90, 0.80)$	726, 572, 413	30, 23, 17	8, 6, 5	2, 2, 2

Note that P^* is the probability of correct selection for the associated subset selection rule, while the error probability γ is controlled at 5 percent level. The identification risk is $0.05 + (1-P^*)$. We can explain the cases described above as follows: for $k = 2$, if the selected subset contains π_i only, we identify H_i^i , $i = 1, 2$; if it contains π_1 and π_2 , we identify H_0 . For $k = 3$, if the selected subset contains π_i only, we identify H_i^i , $i = 1, 2, 3$; if it contains π_1 and π_2 , π_1 and π_3 , or π_2 and π_3 only, we identify H_4^i , H_5^i or H_6^i , respectively. Similar discussion applies to the case $k = 4$.

Now, we discuss the case where σ^2 is unknown. For any i , the maximum likelihood estimators of $\underline{\tau}_i$ and σ^2 are:

$$\hat{\underline{\tau}}_i = (\underline{C}' \Sigma_i^{-1} \underline{C})^{-1} \underline{C}' \Sigma_i^{-1} \underline{y}_i = \begin{bmatrix} y_{i1} \\ \vdots \\ y_{ik} \end{bmatrix}$$

and

$$\hat{\sigma}^2 = \frac{1}{(k-1)(n-1)} \underline{y}_i' [\Sigma_i^{-1} - \Sigma_i^{-1} \underline{C} (\underline{C}' \Sigma_i^{-1} \underline{C})^{-1} \underline{C}' \Sigma_i^{-1}] \underline{y}_i.$$

We know that $\hat{\sigma}^2$ and $\hat{\underline{\tau}}_i$ are independent and the distribution $f(s)$ of $s = \frac{\hat{\sigma}}{\sigma}$ is $\sqrt{\chi_p^2(s)}$ with $p = (k-1)(n-1)$.

As before, we define the selection rule as follows:

$$\varphi_i^0(\hat{\underline{\tau}}_i, \hat{\sigma}) = \begin{cases} 1 & \text{if } y_{i1} + \dots + y_{ik} \geq d_1 \hat{\sigma}, \\ 0 & \text{otherwise} \end{cases},$$

or

$$\varphi_i^0(\underline{x}, \hat{\sigma}) = \begin{cases} 1 & \text{if } \bar{x}_i \geq \frac{1}{k-1} \sum_{j \neq i} \bar{x}_j + \frac{d_1}{k-1} \hat{\sigma} \\ 0 & \text{otherwise} \end{cases}.$$

Conditionally, for an observed value of $\hat{\sigma}$, we can discuss the optimality as before. However, the constant d and n can be determined without any difficulty by (2.8) and (2.9). Since

$$E_{\underline{\tau}} \varphi_i^0(\hat{\underline{\tau}}_i, \hat{\sigma}) = \gamma, \quad \underline{\tau} \in \Omega_0$$

we get

$$(2.6) \quad \int \phi \left[-\frac{d_1 s \sqrt{n}}{\sqrt{(1-\lambda)k(k-1)}} \right] f(s) ds = \gamma,$$

and

$$(2.7) \quad \inf_{\bar{\Omega}} P(CS|\varphi^0) = \int \phi \left[-\frac{(d_1 s - (k-1)\Delta) \sqrt{n}}{\sqrt{(1-\lambda)k(k-1)}} \right] f(s) ds = p^*.$$

This gives

$$(2.8) \quad t \left[-\frac{d_1 \sqrt{n(n-1)}}{\sqrt{(1-\lambda)k}} ; (k-1)(n-1), 0 \right] = \gamma,$$

and

$$(2.9) \quad t \left[-\frac{d_1 \sqrt{n(n-1)}}{\sqrt{(1-\lambda)k}} ; (k-1)(n-1), \frac{\Delta \sqrt{n(k-1)}}{\sqrt{(1-\lambda)k}} \right] = p^*,$$

where $t(a; b, c)$ is the percentage point of the noncentral t with b degrees of freedom and the noncentrality parameter c .

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space, simultaneously. Some examples are provided to illustrate the optimal subset selection rule and its interpretation in terms of the "identified" hypotheses.

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